

Moderating Group Conversation Dynamics with Social Robots

Workshop @RSS 2024 Conference

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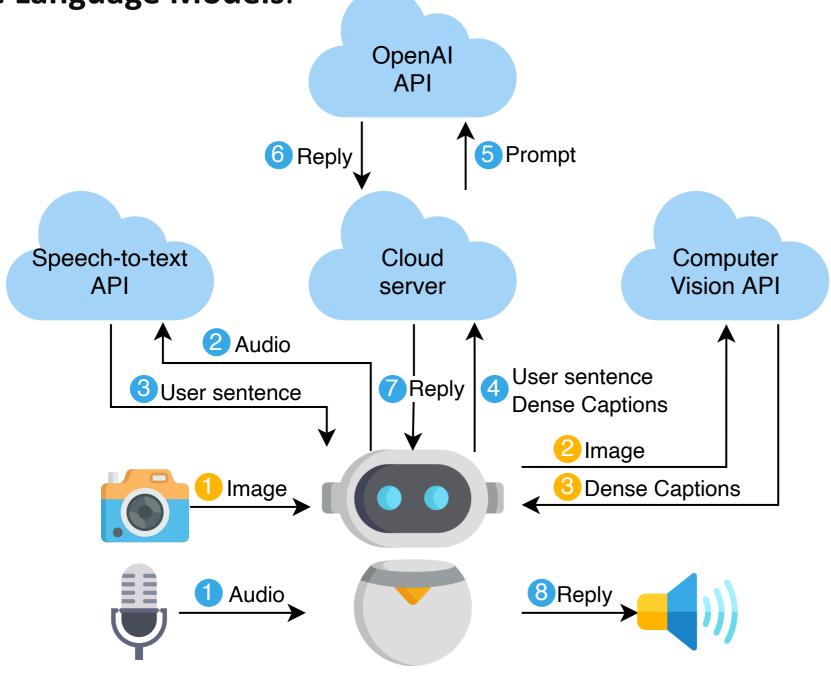
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Q Motivation

Social robotics focuses on creating and applying robots designed to engage with humans in social environments. However, social robots often lack the capabilities to autonomously manage multiparty interactions. This research explores whether social robots can effectively control conversation dynamics in multi-party scenarios by balancing or unbalancing participation and reducing subgroup formation.

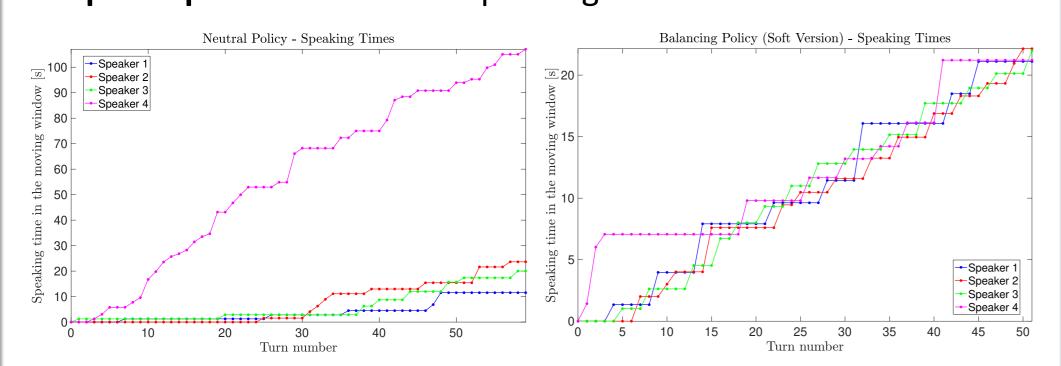
3 System architecture

CAIR (Cloud Artificial Intelligence and Robotics) is a cloud-based architecture for autonomous interaction using an ontology-based knowledge representation and exploiting the power of Large Language Models.

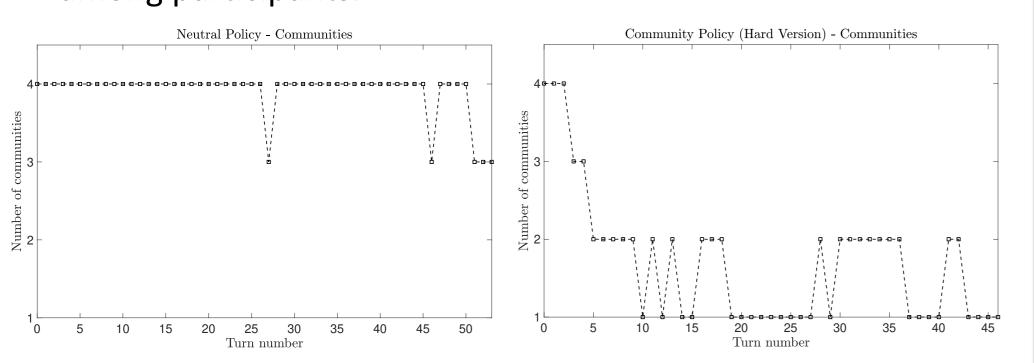


Ralancing and community results

 The Balancing Policy significantly improved balanced participation in terms of speaking time and word count.



The Community Policy reduced the formation of sub-groups among participants.



Objective

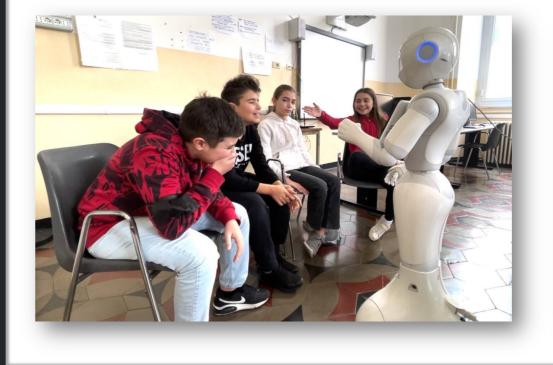
The goal is to develop **easily implementable solutions** on commercially available robotic platforms to **moderate group interactions without negatively impacting user experience**.

© Control policies

- Balancing Policy: Ensures equal participation by actively addressing and encouraging less active speakers.
- Community Policy: Identifies and maintains cohesive subgroups within conversations.

Experiments

Experiments were conducted in a middle school with **300** participants divided into 75 groups of four. Each group interacted with the robot for **15 minutes** using either a **Neutral Policy** (N), a **Balancing Policy** (hard: BH, soft: BS), or a **Community Policy** (hard: CH, soft: CS).





User experience results

Results from the **SASSI questionnaire**, which evaluated the system's *Likeability*, *Cognitive Demand*, and *Annoyance*, showed **consistently positive outcomes** across all conditions. The lack of statistically significant differences between the groups indicates that **the robot's addressing policies did not notably impact user experience**.

| | Mean(Std. Deviation) | | |
|---------------------------|--|--|--|
| | Likeability | Cognitive Demand | Annoyance |
| N BH BS CH CS | 6.21(0.46) 6.25(0.46) 6.14(0.58) 6.18(0.52) 6.09(0.72) | 2.05(0.98) 1.85(0.71) 2.08(0.80) 2.21(0.96) 2.11(0.93) | 2.01(0.70) 1.91(0.76) 1.88(0.69) 1.99(0.66) 2.18(0.89) |

Upcoming trials

- Engagement with passengers on ferries and cruise ship travellers at the maritime station.
- Interaction with elderly people in the hospital's geriatric ward to reduce the incidence of delirium.
- Engagement with children in kindergarten and primary schools to foster interaction.



